

CSI5180. Machine Learning for Bioinformatics Applications

Hidden Markov Models

by

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Preamble

Hidden Markov Models

In this lecture, we focus on learning algorithms suited for **sequence (string) input data**. In particular, we study **Hidden Markov Models**. First, we introduce **Markov processes** and **Markov chains**. Next, using the example of the occasionally dishonest casino, we discern the concept of **hidden variables**. The presentation puts the emphasis on the **graphical nature** of these models. We use the example of a gene finder algorithm as running example.

General objective :

- ✚ **Explain** the concepts related to Hidden Markov Models.

Learning objectives

- ❖ **Discuss** the properties of a Markovian process
- ❖ **Explain** the concept of hidden (latent) variables
- ❖ **Describe** Hidden Markov Models
- ❖ **Name** the important problems (questions) solved by HMM

Reading:

- ❖ Sean R Eddy. What is a hidden Markov model? *Nat Biotechnol* **22**(10):13156, Oct 2004.
- ❖ Byung-Jun Yoon. Hidden Markov Models and their applications in biological sequence analysis. *Curr Genomics* **10**(6):40215, Sep 2009.

Plan

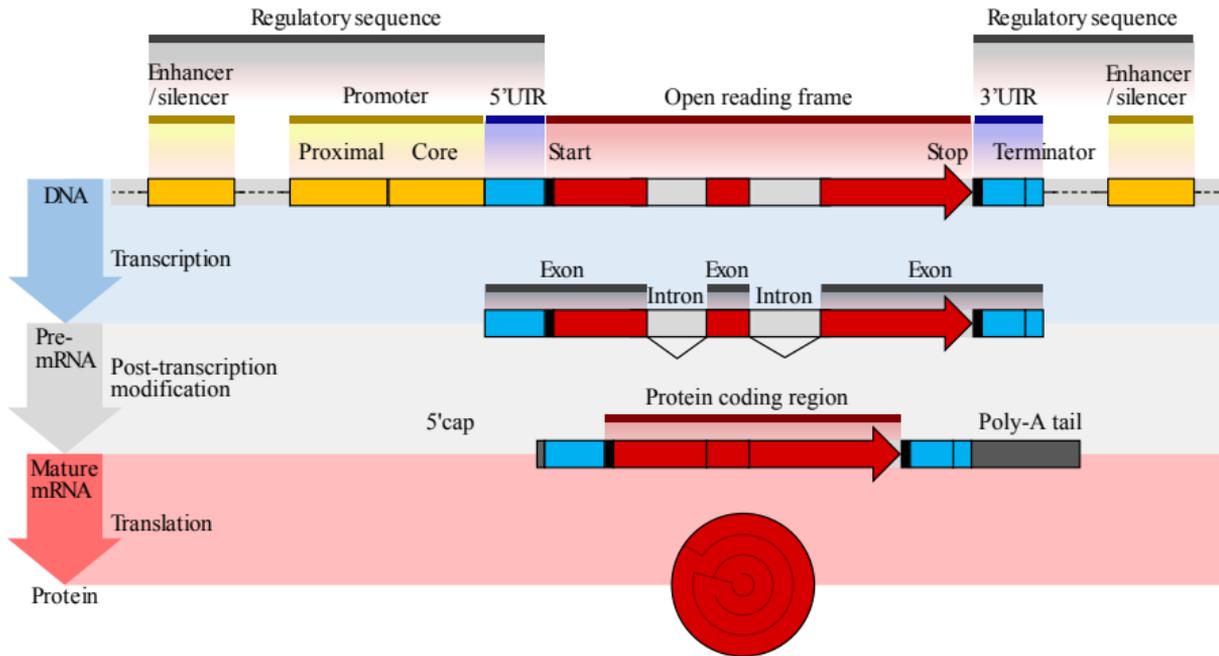
1. Preamble
2. Problem
3. Background information
4. Hidden Markov Model
5. Applications
6. Prologue
7. Appendix

Problem

Gene structure in eukaryotes - the input

```
GAATTCTATATAAATAAGTATTA AATTCTGGTTAAAATATAGAAAAAATAGAATTAGATT
CAATGATATCTAATAACATAACCAAGGAGTAAAGGACTAATTGAGGATGACTAGTCATTCT
ATAATTGGAAGCACGAATGAGGCTAAAAGAATGATAGTATGTTGTTTCGATTCCAAAGGTG
AAAACCAAAGACGGAGAATTCTTATGGAGTCCTGTCTATTTTTATTAACCCTGTGAATTG
AAACATCTTAGTAACAGGAGGAAAAGAAATCAACCGAGATTTTAACGAGTAGTGGCGAGC
GAAAGTAAATGAAAACATTCATGTTTTGATCCGAAATATCTTATCGATGTTTCGATTTTT
TCAAAGACCCCGTACCGGGTCTTGGGGCATGTCTGAAATTGAACATCACACACTTACCCA
TGATAAAGGAGATGGTTTGGATCTTCGATTCTACCATTTTCAGGCAGTGTGTTTATGGAA
TGGGTGGCCAAAGAAGGTGAAAGTCCTGTAAATTTAGTAGTAGACCACTTATGGAGTAG
AACGAATTTTGTTTCAGAAGAAAGGGGTACCATCCTCTAATAAATTA AATATGATAGAATG
AACGATAGTGAAGAGTACCGTGAGGGAAAGTTGAAAAGTACCTCTAAGAGAACGAAGCCT
TCCGAGGCTTCGAATATCAATGCCGGAGGGGTGAAATAGATCCTGAATCAGTTAAGTCTA
AAAGCAGTTTGAGCCAAGATTATGGTGAAGACGTACCTTTTGCATAATGGGTGAGCAAGT
TAATTTTTGGAGCAAGAGAACAAAAGAACGTATCTTTGGTACGTTGGTGATCTAAGTGAA
AACAAAAGAACAAAGTGAGACTTAGTCTTACCCCTATACATAATTTTGCACCTCAGTGTGA
CATGGCCAGGTGTAAGACCGA (. . .52,624,944 . . .)ATCGTAGTAATGCTCTCCGAT
AAGAATCATTGATTCTTCGGACCCACATGGGTACCCATACTCCCCCAAATGA
```

Gene structure in eukaryotes



Source: Thomas Shafee (https://commons.wikimedia.org/wiki/File:Gene_structure_eukaryote_2_annotated.svg)

Gene structure

- ✦ The **gene structure** comprises several elements, including a **transcription start site**, a **5' untranslated region (5' UTR)**, an **open reading frame (ORF)**, a **3' untranslated region (3' UTR)**.

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- ❖ Upstream of the gene, there is a regulatory sequence comprising **enhancers**, **silencers**, and a **promotor**.
- ❖ In **eukaryotes**, genes are made coding segments, called **exons**, and non-coding segments, called **introns**, that need to be removed (spliced) prior to translation.

Gene finding/prediction

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- ❖ **Problem:** identifying the segments of DNA that are making up protein-coding genes.
- ❖ This can be seen as **segmentation** and **labelling** of the DNA sequence.
- ❖ A **Hidden Markov Model** allows representing and integrate these elements into one model. Furthermore, these models have been shown to be effective.

Gene finding/prediction

❖ GENSCAN

- ❖ C Burge and S Karlin. Prediction of complete gene structures in human genomic DNA. *J Mol Biol* **268**(1):7894, Apr 1997.

❖ GENIE

- ❖ Kulp, D., Haussler, D., Reese, M. G. & Eeckman, F. H. A generalized hidden Markov model for the recognition of human genes in DNA. *ISMB International Conference on Intelligent Systems for Molecular Biology* **4**, 134142 (1996).

❖ HMMGENE

- ❖ Krogh, A. Two methods for improving performance of an HMM and their application for gene finding. *ISMB International Conference on Intelligent Systems for Molecular Biology* **5**, 179186 (1997).

Other applications

Other applications include:

1. Modelling **pairwise** and **multiple sequence alignments**
2. **Protein secondary structure** prediction
3. Modelling **transmembrane proteins**

Background information

Remarks

Our presentation will be informal. An entire course could be taught on **Markov chains** and **stochastic processes**.

- ❖ **MAT 4374 Modern Computational Statistics**

Simulation including the rejection method and importance sampling; applications to Monte Carlo Markov chains. Resampling methods such as the bootstrap and jackknife, with applications. Smoothing methods in curve estimation.

- ❖ **MAT 5198 Stochastic Models**

Markov systems, stochastic networks, queuing networks, spatial processes, approximation methods in stochastic processes and queuing theory. Applications to the modelling and analysis of computer-communications systems and other distributed networks.

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 - ❖ A **process can be in any of these states at a given time**; for some **discrete units of time** $t = 0, 1, 2, \dots$
 - ❖ E.g. the type of nucleotide at a given position t in a sequence.

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Markov chains

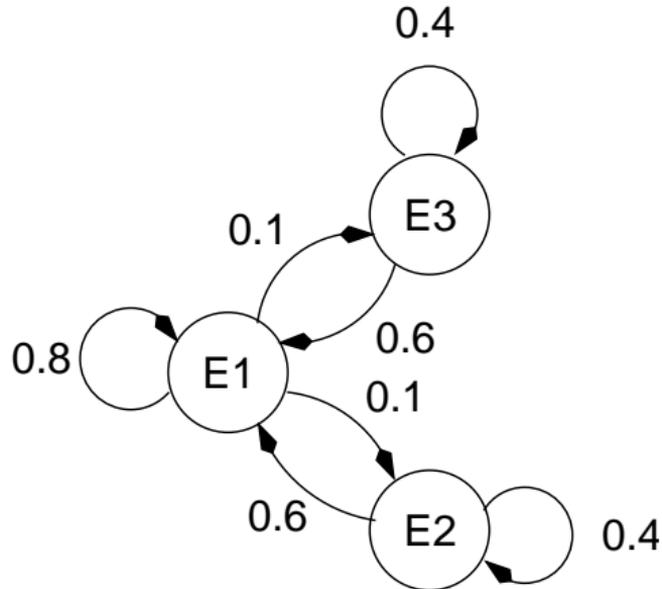
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- ❖ E.g. at time $t + 1$ the amino acid type for a given sequence position either stays the same or is substituted by one of the remaining 19 amino acid types, according to a well-defined probability, to be estimated.

Markov chains



Properties

A (first order) **Markovian process** must conform to the following 2 properties:

1. **Memoryless.** If a process is in state E_i at time t then the probability that it will be in state E_j at time $t + 1$ only depends on E_i (and not on the previous states visited at time $t' < t$, no history). This is called a first-order Markovian process.

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$$P(X_{t+1} = A | X_t = T)$$

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- ❖ A **Markov chain** is a **stochastic (probabilistic) model** describing a **sequence** of events.
- ❖ Herein, we focus on **discrete-time homogeneous finite Markov chain models**.

Markov chain

A (first order) **Markov chain** is a sequence of random variables

$$X_0, \dots, X_{t-1}, X_t$$

that satisfies the following property

$$P(X_t = x_t | X_{t-1} = x_{t-1}, X_{t-2} = x_{t-2}, \dots, X_0 = x_0) = P(X_t = x_t | X_{t-1} = x_{t-1})$$

Markov chain

More generally, a ***m*-order** Markov chain is a sequence of random variables:

$$X_0, \dots, X_{t-1}, X_t$$

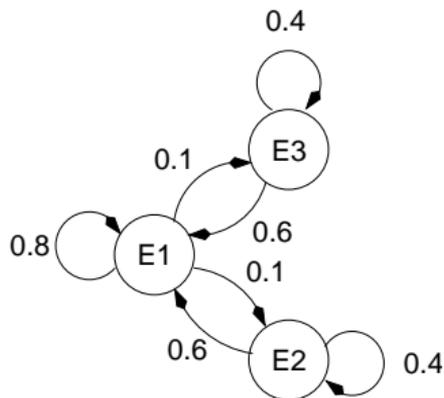
that satisfies the following property

$$\begin{aligned} P(X_t = x_t | X_{t-1} = x_{t-1}, X_{t-2} = x_{t-2}, \dots, X_0 = x_0) \\ = P(X_t = x_t | X_{t-1} = x_{t-1}, \dots, X_{t-m} = x_m) \end{aligned}$$

Markov chain models are denoted M_m , where m is the order of the model, e.g. M_0 , M_1 , M_2 , M_3 , etc. A 0-order model is known as a **Bernoulli model**.

Transition probabilities

The **transition probabilities**, p_{ij} , can be represented graphically,



or as a **transition probability matrix**,

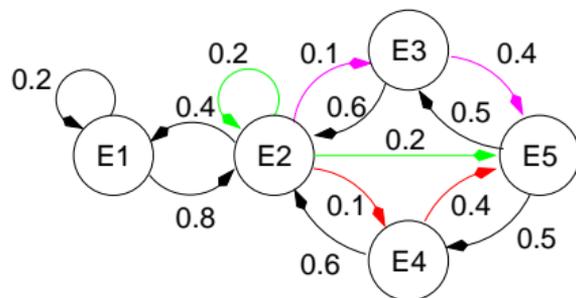
$$P = \begin{bmatrix} 0.8 & 0.1 & 0.1 \\ 0.6 & 0.4 & 0.0 \\ 0.6 & 0.0 & 0.4 \end{bmatrix}$$

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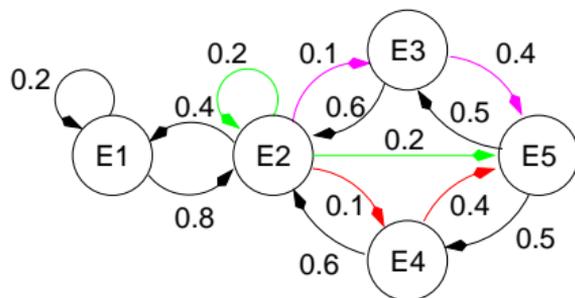
- where p_{ij} is understood as the probability of a transition from state i (row) to state j (column).
- The values in a row represent all the transitions from state i , i.e. all outgoing arcs, and therefore their **sum must be 1**.

Transition probabilities



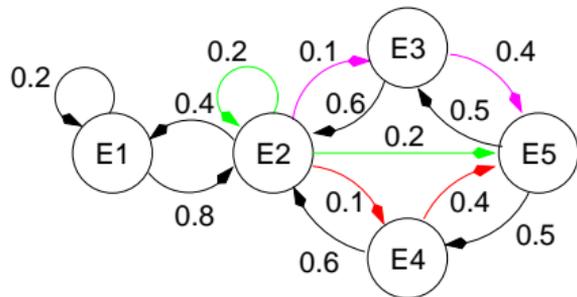
- ❖ The framework allows answering elegantly questions such as this one, “a **Markovian random variable is in state E_i at time t , what is the probability that it will be in state E_j at $t + 2$?**”

Transition probabilities



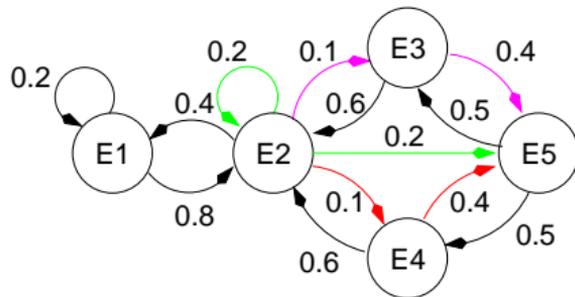
- ❖ The framework allows answering elegantly questions such as this one, “**a Markovian random variable is in state E_i at time t , what is the probability that it will be in state E_j at $t + 2$?**”
- ❖ For the Markovian process graphically depicted above, knowing that a random variable is in state E_2 at time t **what is the probability that it will be in state E_5 at $t + 2$, i.e. after two transitions?**

Transition probabilities



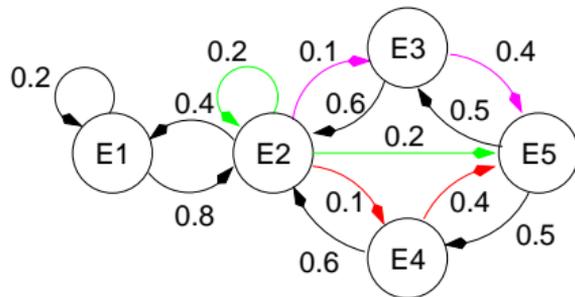
- There are exactly **3 paths of length 2** leading from E_2 to E_5 : (E_2, E_2, E_5) , (E_2, E_3, E_5) and (E_2, E_4, E_5) .

Transition probabilities



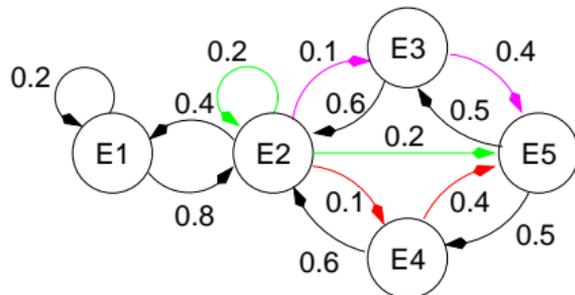
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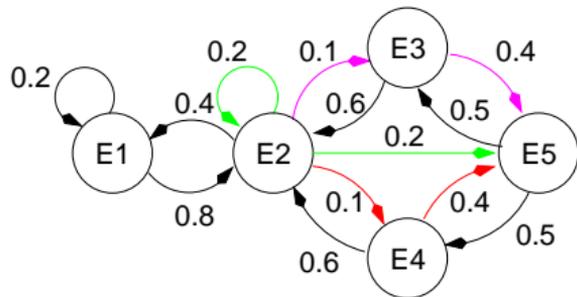
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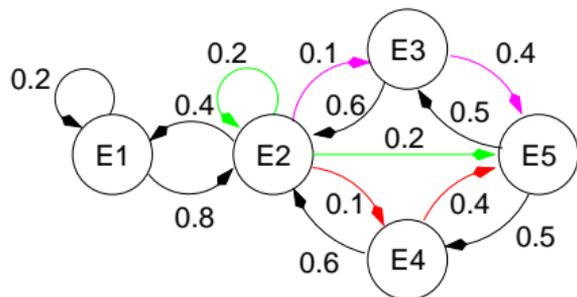


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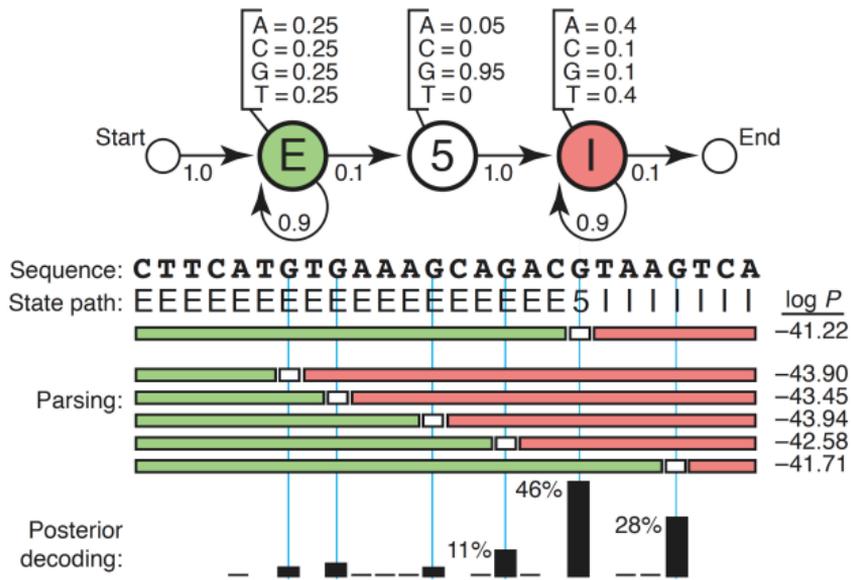
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 - The probability that (E_2, E_4, E_5) is followed is $0.1 \times 0.4 = 0.04$
 - Therefore, the probability that the random variable is found in E_5 at $t + 2$ knowing that it was in E_2 at t is $0.04 + 0.04 + 0.04 = 0.12$.



- ❖ **In general**, the probability that a random variable is found in state E_j at $t + 2$ knowing that it was in E_i at t is,

$$p_{ij}^{(2)} = \sum_k p_{ik} p_{kj}$$

Gene finding



Source: [1] Figure 1

Hidden (latent) variables

What is **hidden**?

Dishonest casino

A **simplified example** will help better understand **hidden variables** and the characteristics of HMMs.

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- ❖ In fact, I will be using **two coins!**
 - ❖ One coin is **fair**, i.e. **head** and **tail** are **equiprobable** outcomes,
 - ❖ but the other one is **loaded** (biased), it returns **head** with probability $\frac{1}{4}$ and tail with probability $\frac{3}{4}$.

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Occasionally dishonest casino

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 - ❖ Looking at a **series of observations**, S , can you predict when the exchanges of coins occurred?

Hidden Markov Model

Hidden Markov Models (HMM)

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Yoon, B.-J. Hidden Markov Models and their Applications in Biological Sequence Analysis. *Current Genomics* **10**, 402415 (2009).

Definitions

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- ❖ The sequence of states, denoted by π and called the **path**, is modelled as a **Markov chain**, these transitions are not directly observable (they are **hidden**),

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- ❖ Each state has **emission** probabilities associated with it:

$$e_k(b) = P(S(i) = b | \pi_i = k)$$

the probability of **observing**/emitting the symbol b when in state k .

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- ❖ Remembering our discussion about **finite state automata**, an **HMM** is equivalent to a **stochastic regular grammar**.

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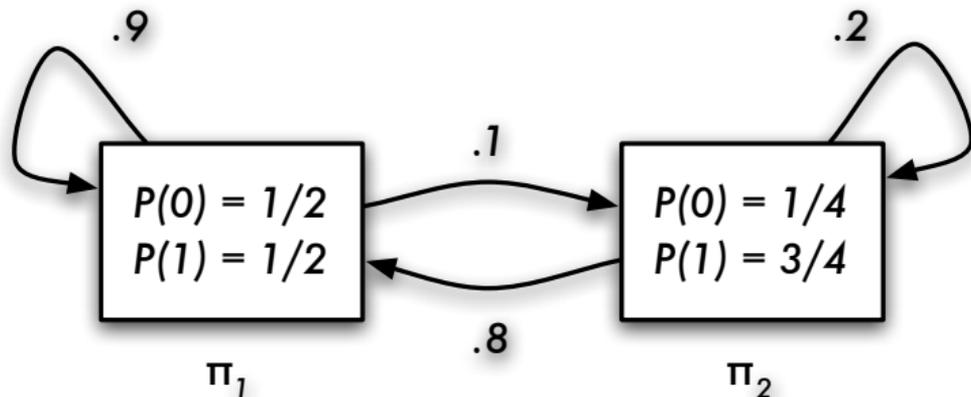
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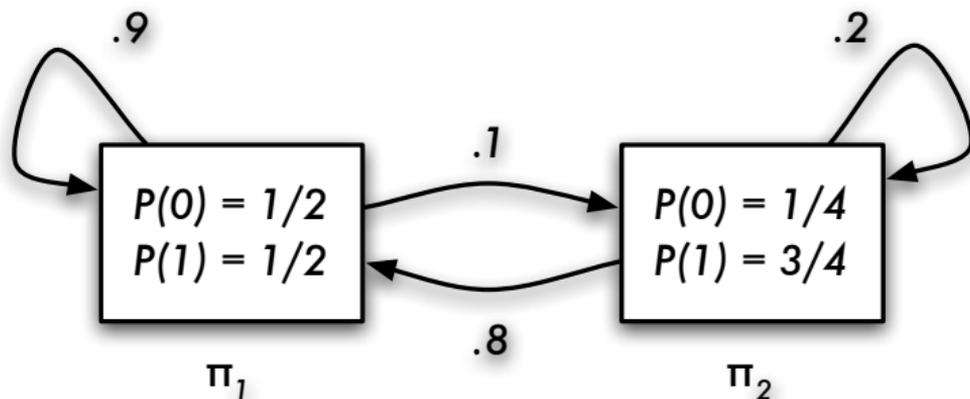
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 - ❖ Let's call this the **parameter estimation problem**.

Occasionally dishonest casino



- Modelled using an **HMM**, where **each state represents a coin**, with its own **emission probability distribution**, and the **transition probabilities** represent exchanging the coins.

Worked example

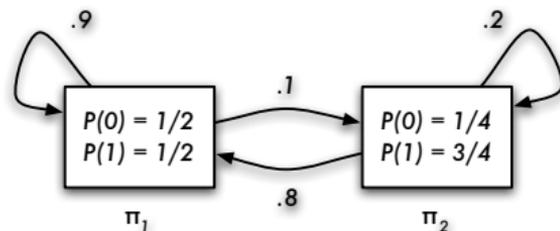


- Given an **input sequence of symbols** (heads and tails), such as 0, 1, 1, 0, 1, 1, 1, which **sequence of states** has the highest probability?

Worked example

Which path leads to the highest joint probability?

S	0	1	1	0	1	1	1
π	π_1						
π	π_1	π_1	π_1	π_1	π_1	π_1	π_2
...							
π	π_2	π_2	π_1	π_1	π_2	π_2	π_2
...							
π	π_2						



Brute-force

- ✦ Since the game consists of printing the series of switches from one coin to the other, selecting the path with the **highest joint probability**, $P(S, \pi)$, seems appropriate.

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Brute-force

- ❖ Since the game consists of printing the series of switches from one coin to the other, selecting the path with the **highest joint probability**, $P(S, \pi)$, seems appropriate.
- ❖ Here, there are $2^7 = 128$ possible paths, **enumerating all** of them is feasible.
- ❖ However, the number of states and consequently the number of possible paths are generally much larger: $\mathcal{O}(M^L)$, where M is the number of states and L is the length of the sequence of symbols.

Decoding problem

- Given an observed sequence of symbols, S , **the decoding problem** consists of finding a sequence of states, π , such that the joint probability of S and π is maximum.

$$\operatorname{argmax}_{\pi} P(S, \pi)$$

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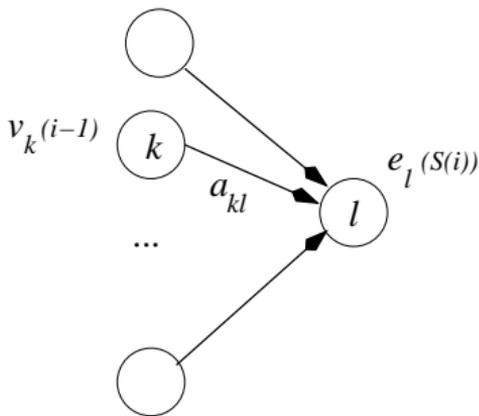
$$\operatorname{argmax}_{\pi} P(S, \pi)$$

- For our game, the sequence of states is of interest because it serves to predict the exchanges of coins.

Decoding problem — Viterbi

- ❖ The **most probable path** can be found **recursively**. The score for the most probable path ending in state l with observation i , noted $v_l(i)$, is given by,

$$v_l(i) = e_l(S(i)) \max_k [v_k(i-1) a_{kl}]$$



where k is running for states such that a_{kl} is defined.

Decoding problem

- ❖ The algorithm for solving the decoding problem is known as the **Viterbi algorithm**. It finds the best (most probable) path using the **dynamic programming** technique.
 - ❖ **Forward.** This requires filling the table v , for all i and for all l — see the definition of $v_l(i)$ on the previous slide.
 - ❖ **Traceback.** Starting with $v_{end}(n)$, the algorithm reverses the computation to find the path with maximum joint probability.
- ❖ Sean R Eddy, What is dynamic programming?, *Nat Biotechnol* **22**:7, 90910, 2004.

Decoding problem — table v

	$S(1)$	$S(2)$	$S(3)$		$S(n-1)$	$S(n)$
π_1	<input type="text"/>	<input type="text"/>	<input type="text"/>	...	<input type="text"/>	<input type="text"/>
π_2	<input type="text"/>	<input type="text"/>	<input type="text"/>		<input type="text"/>	<input type="text"/>
...						
π_m	<input type="text"/>	<input type="text"/>	<input type="text"/>		<input type="text"/>	<input type="text"/>

Decoding problem — gene finding

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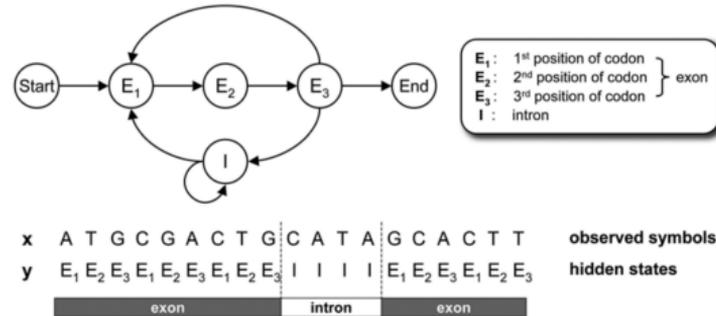
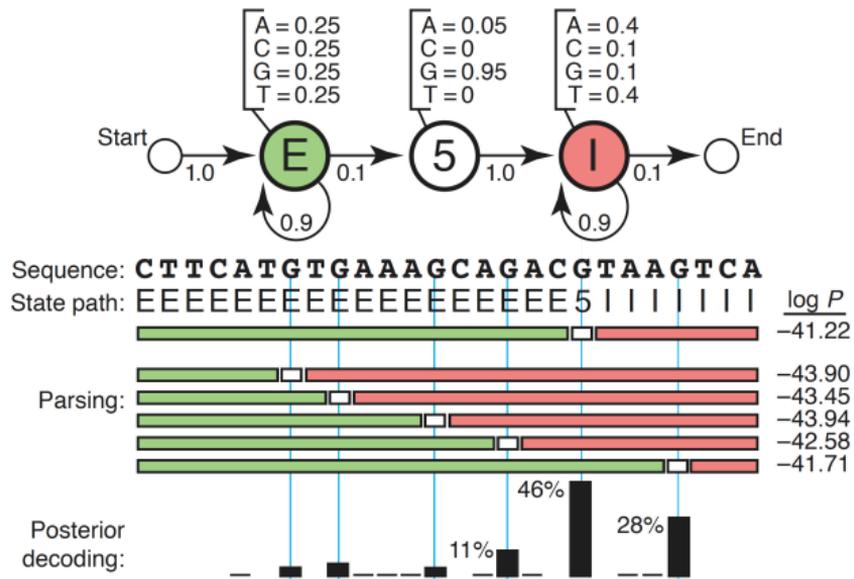


Fig. (1). A simple HMM for modeling eukaryotic genes.

Source: [2] Figure 1

- For a given input sequence, the **decoding problem** reveals the path with maximum joint probability. Effectively telling us the nucleotides that are likely to be in **exons** (states E_1 , E_2 , E_3) and those that likely to be in **introns** (state I).

Decoding problem — Gene finding



Source: [1] Figure 1

The likelihood problem: calculating $P(S|\theta)$

- In the case of a **Markov chain** there is a single path for a given sequence S and therefore $P(S|\theta)$ is given by,

$$P(S|\theta) = P(S(1)) \prod_{i=2}^n a_{S(i-1)S(i)}$$

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- ❖ In the case of an **HMM**, there are several paths producing the same S (some paths will be more likely than others) and $P(S|\theta)$ should be defined as the sum of all the probabilities of all possible paths producing S ,

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$$P(S|\theta) = \sum_{\pi} P(S, \pi)$$

- ❖ The number of paths grows **exponentially** with respect to the **length of the sequence**, therefore all the paths cannot simply be enumerated and summed.

The likelihood problem: forward algorithm

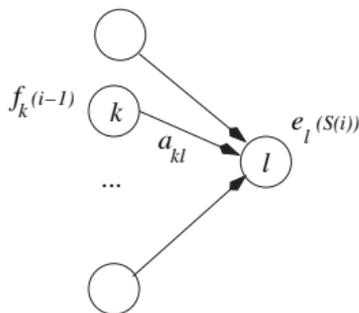
- ❖ Modifying the Viterbi algorithm **changing the maximization** by a **sum** calculates the probability of the observed sequence up to position i ending in state l ,

$$f_l(i) = e_l(S(i)) \sum_k f_k(i-1) a_{kl}$$

The likelihood problem

- ❖ The score represents the probability of the sequence up to (and including) $S(i)$, noted $f_l(i)$, is given by,

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where k is running for states such that a_{kl} is defined.

Model specification

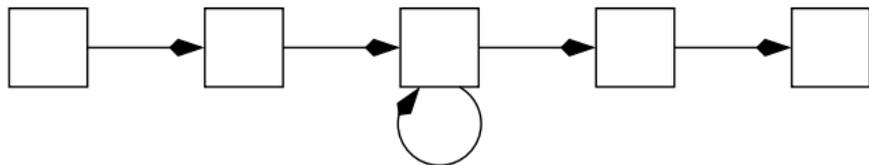
- ❖ We now turn to our third and final question. **How to determine the parameters of the model?**
- ❖ Let x_1, \dots, x_N be N independent examples forming the training set (typically, N sequences of observable symbols), the objective is to find a set parameters, θ , such that:

$$\max_{\theta} \prod_{i=1}^N P(x_i|\theta)$$

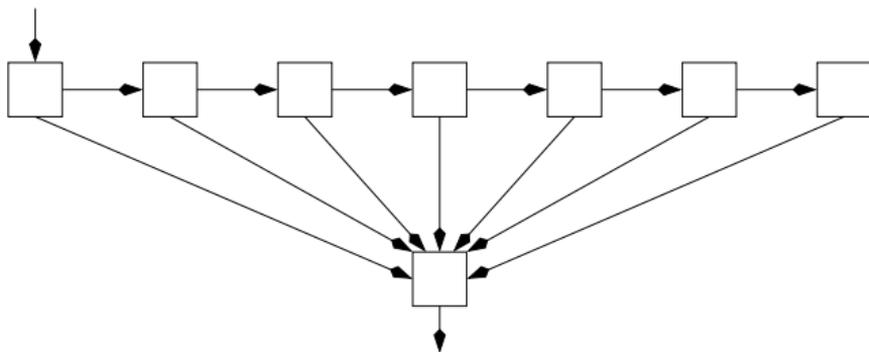
Model Specification

- ❖ **Structure (topology): states + interconnect**
- ❖ Estimating the **transition/emission probabilities**

Modelling the length

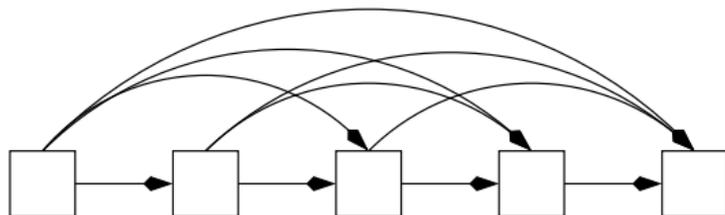


At least 5 symbols long

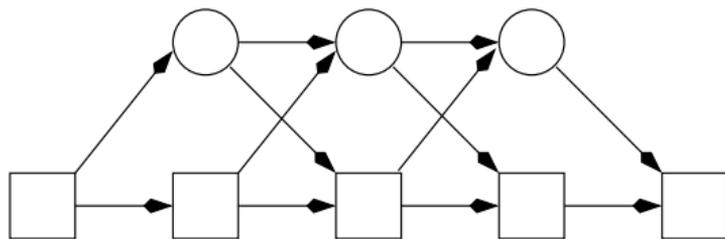


2 to 8 symbols long

Arbitrary deletions



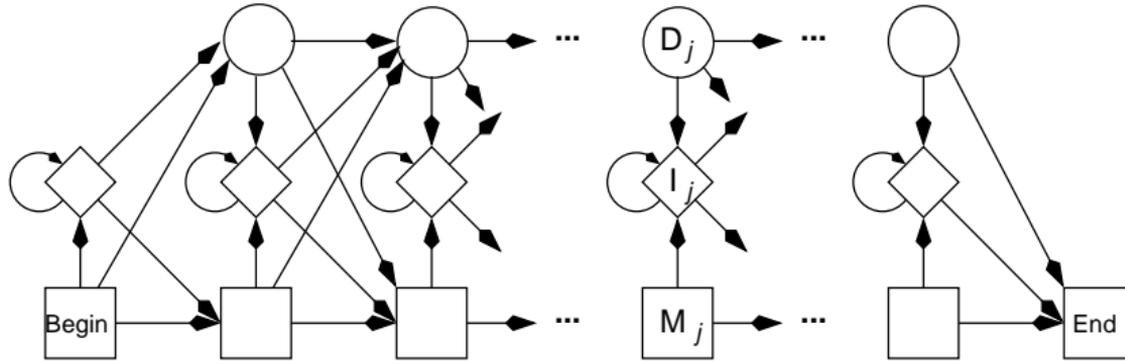
Too expensive, too many parameters to evaluate!



Silent (null) states do not emit symbols.

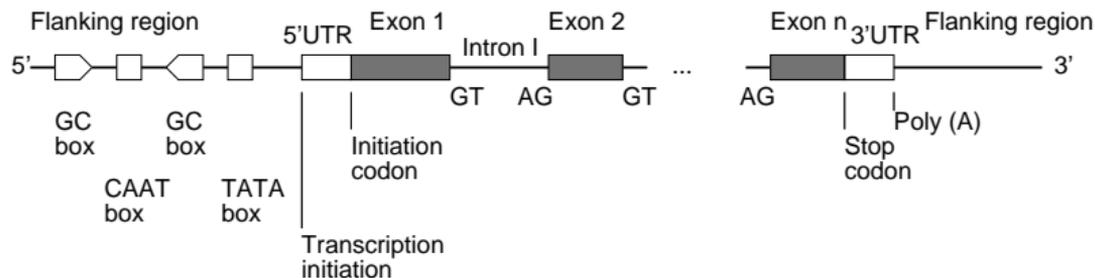
⇒ Silent states prevent modelling specific distant transitions.

Profile HMMs



⇒ Models insertion/deletions separately.

Gene prediction



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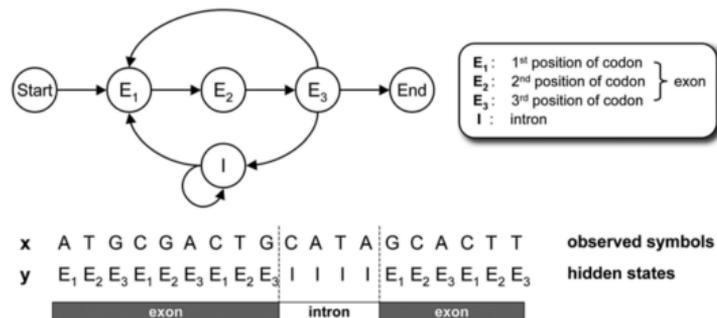


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The parameter estimation problem

❖ **Problem:** estimate the a_{st} and $e_k(b)$ probabilities.

Given:

- ❖ a **fixed topology**;
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Two scenarios:

- ❖ The paths are **known** (existing annotated genes)
- ❖ The paths are **unknown**

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Sometimes called the **Baum-Welch** algorithm. **Gradient descent** can also be used.

- ❖ Chuong B Do and Serafim Batzoglou, What is the expectation maximization algorithm?, *Nat Biotechnol* **26**:8, 897899, 2008.

Applications

- ❖ **sklearn.hmm** has been “deprecated due to it no longer matching the scope and the API of the project.” It was removed starting with the release 0.17 [as of writing this, the current version of Scikit-Learn is 0.21.3].
- ❖ **Pomegranate** implements probabilistic models, including hidden Markov models.
 - ❖ Documentation
- ❖ Most of the time, hidden Markov models are implemented in specialized tools, such as **GENSCAN**, **GENIE**, **HMMGENE**, **UGENE**, **SAM**, **HMMER**, etc.

- ❖ Eddy, S. R. Profile hidden Markov models. *Bioinformatics* **14**, 755763 (1998).
 - ❖ 3371 citations according to Scopus
- ❖ J. Mistry, R. D. Finn, S. R. Eddy, A. Bateman, M. Punta. Challenges in Homology Search: HMMER3 and Convergent Evolution of Coiled-Coil Regions. *Nucleic Acids Research* **41**:e121, 2013.
- ❖ <http://hmmer.org/publications.html>
- ❖ <http://hmmer.org>

- ❖ “The **Pfam** database is a large collection of protein families, each represented by multiple sequence alignments and **hidden Markov models** (HMMs).”
- ❖ E.L.L. Sonnhammer, S.R. Eddy and R. Durbin. Pfam: a comprehensive database of protein families based on seed alignments. *Proteins* **28**:405-420, 1997.
 - ❖ 806 citations according to Scopus
- ❖ S. El-Gebali, *et al.* The Pfam protein families database in 2019. *Nucleic Acids Research* (2019), doi: 10.1093/nar/gky995
- ❖ Pfam **32.0**, September 2018, **17,929 entries**
- ❖ <https://pfam.xfam.org>

Prologue

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- ❖ Those probabilities do not depend on the value of t . This property is called **homogeneity of time**. Here, time is finite.
- ❖ A **hidden Markov model** comprises two elements: a sequence of **observable symbols** and a **sequence of hidden states**.

Next module

❖ Support Vector Machine

Appendix

Decoding problem

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 2. or 2) $S(1)$ could have been produced from π_2 , and there was a transition π_2 to π_1 .
- ❖ The two joint probabilities would be $P(S(1)|\pi_1)P(\pi_1 \rightarrow \pi_1)P(S(2)|\pi_1)$ and $P(S(1)|\pi_2)P(\pi_2 \rightarrow \pi_1)P(S(2)|\pi_1)$.

Decoding problem

- Now consider an observed sequence of length three, let's assume that the last symbol is 1, what is the probability of that symbol being emitted from state π_1 ?
- There are two ways of ending up in π_1 while producing $S(3)$:
 - the last state that led to the production of the sequence of symbols $S[1, 2]$ was π_1 and the state remained π_1 ,
 - the last state that led to the production of the sequence of symbols $S[1, 2]$ was π_2 and it is followed by a transition π_2 to π_1 , with probability a_{21} .

Let's define $v_k(i)$ as **the probability of the most probable path ending in state k while producing the observation i** . Using this notation for formulating the probabilities for the above two scenarios.

$$v_1(3) = \max [v_1(2) \times a_{11} \times e_1(0), v_2(2) \times a_{21} \times e_1(0)]$$

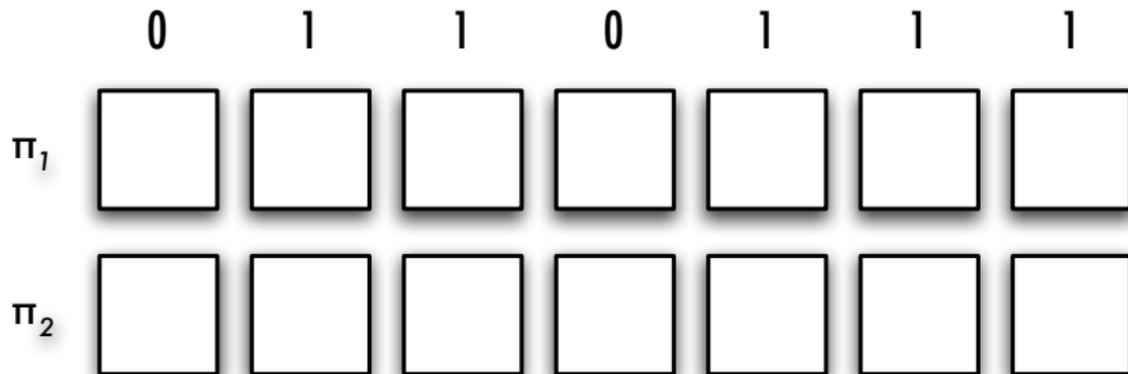
Decoding problem

- For our 2 states HMM, we can write the following equation,

$$v_1(i) = \max [v_1(i-1) \times a_{11} \times e_1(S(i)), v_2(i-1) \times a_{21} \times e_1(S(i))]$$

$$v_2(i) = \max [v_1(i-1) \times a_{12} \times e_2(S(i)), v_2(i-1) \times a_{22} \times e_2(S(i))]$$

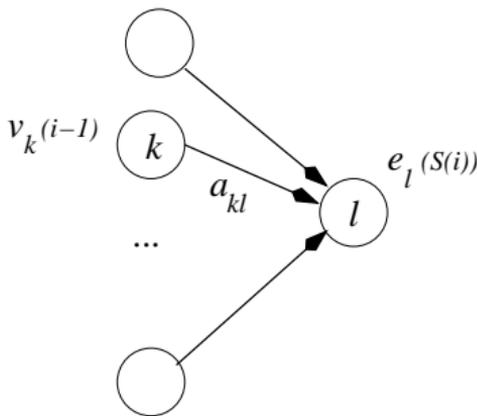
Decoding problem



Decoding problem

- ❖ The **most probable path** can be found **recursively**. The score for the most probable path ending in state l with observation i , noted $v_l(i)$, is given by,

$$v_l(i) = e_l(S(i)) \max_k [v_k(i-1) a_{kl}]$$



where k is running for states such that a_{kl} is defined.

Decoding problem

- ❖ The algorithm for solving the decoding problem is known as the **Viterbi algorithm**. It finds the best (most probable) path using the **dynamic programming** technique.
 - ❖ **Forward.** First, this requires filling the table v , for all i and for all l — see the definition of $v_l(i)$ on the previous slide.
 - ❖ **Traceback.** Next, starting with $v_{end}(n)$, the algorithm reverses the computation to find the path with maximum joint probability.
- ❖ Sean R Eddy, What is dynamic programming?, *Nat Biotechnol* **22**:7, 90910, 2004.

Decoding problem: Viterbi algorithm

Initialization:

$$v_0 = 1, v_k = 0, k > 0$$

Recurrence:

$$v_l(i) = e_l(S(i)) \max_k (v_k(i-1) a_{kl})$$

where, $v_k(i)$ represents the probability of the most probable path ending in state k and position i in S .

- A pointer (backward) is kept from l to the value of k that maximizes $v_k(i-1) a_{kl}$.

⇒ **Implementation issues:** because of the products (small) probabilities leads to underflow the algorithm is implemented using the logarithm of the values and therefore the products becomes sums.

Decoding problem — table v

	$S(1)$	$S(2)$	$S(3)$		$S(n-1)$	$S(n)$
π_1	<input type="text"/>	<input type="text"/>	<input type="text"/>	...	<input type="text"/>	<input type="text"/>
π_2	<input type="text"/>	<input type="text"/>	<input type="text"/>		<input type="text"/>	<input type="text"/>
...						
π_m	<input type="text"/>	<input type="text"/>	<input type="text"/>		<input type="text"/>	<input type="text"/>

Decoding problem

```
# transition probabilities (t)
$t[0][0] = 0.9; $t[0][1] = 0.1;
$t[1][0] = 0.2; $t[1][1] = 0.8;

# emission probabilities (e)
$e[0][0] = 0.50; $e[0][1] = 0.50;
$e[1][0] = 0.05; $e[1][1] = 0.95;

# observed sequence (S)
@S = (0, 1, 0, 1, 0, 1, 1, 1, 1, 1, 1);

# initialization (d is the dynamic programming table)
$d[ 0 ][ 0 ] = $e[ 0 ][ $S[ 0 ] ];
$d[ 1 ][ 0 ] = $e[ 1 ][ $S[ 0 ] ];
```

Decoding problem

```
for ( $j=1; $j < @S; $j++ ) {  
  for ( $i=0; $i <= 1; $i++ ) {  
    $m = 0;  
    for ( $k=0; $k <= 1; $k++ ) {  
      $v = $d[$k][$j-1]*$t[$k][$i]*$e[$i][$S[$j]];  
      if ( $v > $m ) {  
        $from = $k; $to = $i; $m = $v;  
      }  
    }  
    $d[ $i ][ $j ] = $m;  
    $tr[ $i ][ $j ] = "($from->$to)";  
  }  
}
```

Decoding problem

```
for ( $i=0; $i <= 1; $i++ ) {  
    for ( $j=0; $j < @S; $j++ ) {  
        printf "\t%5.5f", $d[ $i ][ $j ];  
    }  
    print "\n";  
    for ( $j=0; $j < @S; $j++ ) {  
        printf "\t %s", $tr[ $i ][ $j ];  
    }  
    print "\n";  
}
```

Decoding problem

$t[0][0] = 0.9$; $t[0][1] = 0.1$; $t[1][0] = 0.2$; $t[1][1] = 0.8$;
 $e[0][0] = 0.50$; $e[0][1] = 0.50$; $e[1][0] = 0.05$; $e[1][1] = 0.95$;

	0	1	0	1	0	1	1	1	1	1	1	1
0.50000	0.22500	0.10125	0.04556	0.02050	0.00923	0.00415	0.00187	0.00084	0.00038	0.00017	0.00008	
	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)	(0→0)
0.05000	0.04750	0.00190	0.00962	0.00038	0.00195	0.00148	0.00113	0.00086	0.00065	0.00049	0.00038	
	(0→1)	(1→1)	(0→1)	(1→1)	(0→1)	(1→1)	(1→1)	(1→1)	(1→1)	(1→1)	(1→1)	(1→1)

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